

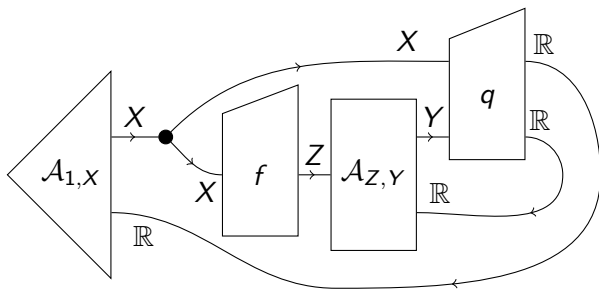
Compositional game theory

Jules Hedges

(University of Oxford)

SYCO 1, Birmingham
21 September 2018

A peek at where we're going



Game theory

- Mathematical theory of **interacting “rational” agents**
- **Players** make **observations** and then make **choices**
- Group choices determine **payoffs**
- “Local view” of rationality: players act to maximise payoff
- “Global view”: equilibrium strategies

Example: penalty shootout



$$a, b \in \{L, R\}$$

Example: penalty shootout



$$a, b \in \{L, R\}$$

$$\pi(a, b) = \begin{cases} (+1, -1) & \text{if } a \neq b \\ (-1, +1) & \text{if } a = b \end{cases}$$

Example: penalty shootout



$$a, b \in \{L, R\}$$

$$\pi(a, b) = \begin{cases} (+1, -1) & \text{if } a \neq b \\ (-1, +1) & \text{if } a = b \end{cases}$$

Unique (probabilistic) equilibrium: $a = b = \frac{1}{2} |L\rangle + \frac{1}{2} |R\rangle$

Example: penalty shootout



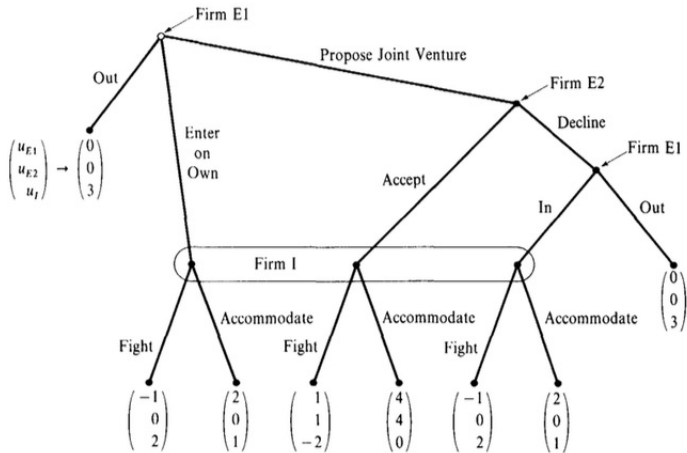
$$a, b \in \{L, R\}$$

$$\pi(a, b) = \begin{cases} (+1, -1) & \text{if } a \neq b \\ (-1, +1) & \text{if } a = b \end{cases}$$

Unique (probabilistic) equilibrium: $a = b = \frac{1}{2} |L\rangle + \frac{1}{2} |R\rangle$

Nash's theorem generalises this situation

Picturing game theory (1945 – 2018)



Game theory has some issues

- Well known: equilibrium as behavioural prediction is experimentally falsified (e.g. ultimatum game)

Game theory has some issues

- Well known: equilibrium as behavioural prediction is experimentally falsified (e.g. ultimatum game)
- Harsanyi type spaces are accurate but **underfit** (and mathematically hard!)

Game theory has some issues

- Well known: equilibrium as behavioural prediction is experimentally falsified (e.g. ultimatum game)
- Harsanyi type spaces are accurate but **underfit** (and mathematically hard!)
- There is no accepted **operational theory** (or “equilibrating process”) (c.f. evolutionary game theory)

Game theory has some issues

- Well known: equilibrium as behavioural prediction is experimentally falsified (e.g. ultimatum game)
- Harsanyi type spaces are accurate but **underfit** (and mathematically hard!)
- There is no accepted **operational theory** (or “equilibrating process”) (c.f. evolutionary game theory)
- Serious computability/complexity issues (algorithmic game theory)

Game theory has some issues

- Well known: equilibrium as behavioural prediction is experimentally falsified (e.g. ultimatum game)
- Harsanyi type spaces are accurate but **underfit** (and mathematically hard!)
- There is no accepted **operational theory** (or “equilibrating process”) (c.f. evolutionary game theory)
- Serious computability/complexity issues (algorithmic game theory)
- Ordinary games do not compose/scale

The fundamental headache of social science

Beliefs have causal effects

Defining **PC**

PC is a category where:

- Objects are pairs of sets $\begin{pmatrix} X \\ S \end{pmatrix}$
- Morphisms $\lambda : \begin{pmatrix} X \\ S \end{pmatrix} \rightarrow \begin{pmatrix} Y \\ R \end{pmatrix}$ are pairs of functions:
 - $v_\lambda : X \rightarrow Y$
 - $u_\lambda : X \times R \rightarrow S$

λ is called a **lens**

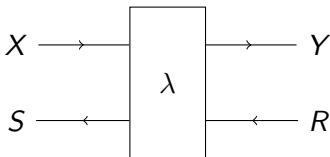
Defining PC

PC is a category where:

- Objects are pairs of sets $\begin{pmatrix} X \\ S \end{pmatrix}$
- Morphisms $\lambda : \begin{pmatrix} X \\ S \end{pmatrix} \rightarrow \begin{pmatrix} Y \\ R \end{pmatrix}$ are pairs of functions:
 - $v_\lambda : X \rightarrow Y$
 - $u_\lambda : X \times R \rightarrow S$

λ is called a **lens**

We draw it like this:



Intuition for PC

Approximately ...

- First part: **physical** information
 - X and Y are sets of things an agent can **observe** or **choose**

Intuition for PC

Approximately ...

- First part: **physical** information
 - X and Y are sets of things an agent can **observe** or **choose**
- Second part: **teleological** or **counterfactual** information
 - R and S are sets of things an agent can **optimise** or **have preferences** about

Intuition for PC

Approximately ...

- First part: **physical** information
 - X and Y are sets of things an agent can **observe** or **choose**
- Second part: **teleological** or **counterfactual** information
 - R and S are sets of things an agent can **optimise** or **have preferences** about

A typical example:

- $f : X \rightarrow Y$ is a function
- Promote to $\lambda : \left(\mathbb{R}\right)^X \rightarrow \left(\mathbb{R}\right)^Y$ with $v_\lambda = f$
- $u_\lambda : X \times \mathbb{R} \rightarrow \mathbb{R}$ is **backpropagation of value**
- If we know x and we know the value of $f(x)$ then u_λ tells us what the value of x was

Example: a decision process

(aka. a Markov decision process without the probability)

Take a **state space** S , actions A , **transition function**

$$f : S \times A \rightarrow S \times \mathbb{R}$$

Example: a decision process

(aka. a Markov decision process without the probability)

Take a **state space** S , actions A , **transition function**

$$f : S \times A \rightarrow S \times \mathbb{R}$$

Every **policy function** $\sigma : S \rightarrow A$ determines a lens $\lambda : \left(\begin{smallmatrix} S \\ \mathbb{R} \end{smallmatrix}\right) \rightarrow \left(\begin{smallmatrix} S \\ \mathbb{R} \end{smallmatrix}\right)$
by

- $v_\lambda(s) = f(s, \sigma(s))_1$
- $u_\lambda(s, u) = f(s, \sigma(s))_2 + \beta \cdot u$
- $0 < \beta < 1$ is **discount factor**

Composing lenses

Given

$$\begin{pmatrix} X \\ S \end{pmatrix} \xrightarrow{\lambda} \begin{pmatrix} Y \\ R \end{pmatrix} \xrightarrow{\mu} \begin{pmatrix} Z \\ Q \end{pmatrix}$$

we can compose them to $\mu \circ \lambda : \begin{pmatrix} X \\ S \end{pmatrix} \rightarrow \begin{pmatrix} Z \\ Q \end{pmatrix}$

(Important non-obvious fact: this is associative)

Composing lenses

Given

$$\begin{pmatrix} X \\ S \end{pmatrix} \xrightarrow{\lambda} \begin{pmatrix} Y \\ R \end{pmatrix} \xrightarrow{\mu} \begin{pmatrix} Z \\ Q \end{pmatrix}$$

we can compose them to $\mu \circ \lambda : \begin{pmatrix} X \\ S \end{pmatrix} \rightarrow \begin{pmatrix} Z \\ Q \end{pmatrix}$

(Important non-obvious fact: this is associative)

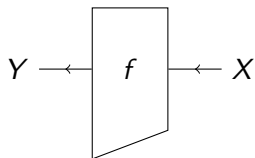
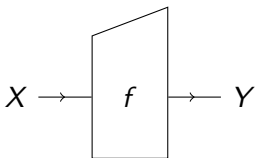
Given $\begin{pmatrix} X_1 \\ S_1 \end{pmatrix} \xrightarrow{\lambda_1} \begin{pmatrix} Y_1 \\ R_1 \end{pmatrix}$ and $\begin{pmatrix} X_2 \\ S_2 \end{pmatrix} \xrightarrow{\lambda_2} \begin{pmatrix} Y_2 \\ R_2 \end{pmatrix}$ we can compose them to

$$\begin{pmatrix} X_1 \times X_2 \\ S_2 \times S_1 \end{pmatrix} \xrightarrow{\lambda_1 \otimes \lambda_2} \begin{pmatrix} Y_1 \times Y_2 \\ R_2 \times R_1 \end{pmatrix}$$

PC is a symmetric monoidal category

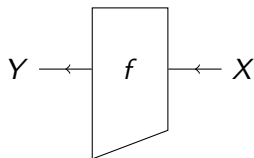
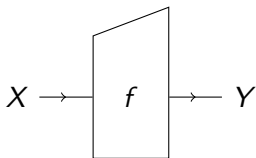
Special lenses

$f : X \rightarrow Y$ lifts to $f : \begin{pmatrix} X \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} Y \\ 1 \end{pmatrix}$ or $f^* : \begin{pmatrix} 1 \\ Y \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ X \end{pmatrix}$



Special lenses

$f : X \rightarrow Y$ lifts to $f : \begin{pmatrix} X \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} Y \\ 1 \end{pmatrix}$ or $f^* : \begin{pmatrix} 1 \\ Y \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ X \end{pmatrix}$



Special case: Every $\begin{pmatrix} X \\ 1 \end{pmatrix}$ is a comonoid, every $\begin{pmatrix} 1 \\ X \end{pmatrix}$ is a monoid

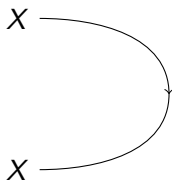
Special lenses

$f : X \rightarrow Y$ lifts to $f : \begin{pmatrix} X \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} Y \\ 1 \end{pmatrix}$ or $f^* : \begin{pmatrix} 1 \\ Y \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ X \end{pmatrix}$



Special case: Every $\begin{pmatrix} X \\ 1 \end{pmatrix}$ is a comonoid, every $\begin{pmatrix} 1 \\ X \end{pmatrix}$ is a monoid

There is canonical $\varepsilon_X : \begin{pmatrix} X \\ X \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ (but no η !)

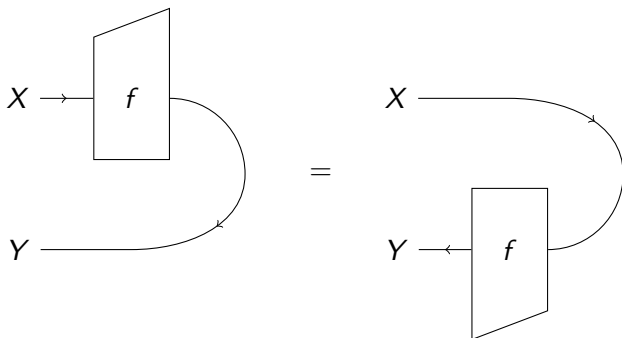


The counit law

Theorem:

$$\varepsilon_Y \circ ((f, 1) \otimes (1, \text{id}_Y)) = \varepsilon_X \circ ((\text{id}_X, 1) \otimes (1, f))$$

aka:



Interesting facts about **PC**

- **PC** is a **dialectica category** over a 1-valued logic
 - hence, a sound model of linear logic

Interesting facts about PC

- **PC** is a **dialectica category** over a 1-valued logic
 - hence, a sound model of linear logic
- $\left(\begin{smallmatrix} X \\ S \end{smallmatrix}\right) \mapsto X, \lambda \mapsto v_\lambda$ is a fibration
 - It's fibrewise opposite of Jacobs' **simple fibration**

Interesting facts about **PC**

- **PC** is a **dialectica category** over a 1-valued logic
 - hence, a sound model of linear logic
- $\left(\begin{smallmatrix} X \\ S \end{smallmatrix}\right) \mapsto X, \lambda \mapsto v_\lambda$ is a fibration
 - It's fibrewise opposite of Jacobs' **simple fibration**
- Hot off the press: **PC** is complete (if underlying cat is complete, cocomplete, cartesian closed, ...)
 - Work in progress: game theory using **Span(PC)**

Interesting facts about **PC**

- **PC** is a **dialectica category** over a 1-valued logic
 - hence, a sound model of linear logic
- $\left(\begin{smallmatrix} X \\ S \end{smallmatrix}\right) \mapsto X, \lambda \mapsto v_\lambda$ is a fibration
 - It's fibrewise opposite of Jacobs' **simple fibration**
- Hot off the press: **PC** is complete (if underlying cat is complete, cocomplete, cartesian closed, ...)
 - Work in progress: game theory using **Span(PC)**
- Really hot off the press: **PC** can be defined over a monoidal category:

$$\text{hom}_{\mathbf{PC}(\mathcal{C})} \left(\left(\begin{smallmatrix} X \\ S \end{smallmatrix} \right), \left(\begin{smallmatrix} Y \\ R \end{smallmatrix} \right) \right) = \int^{A \in \mathcal{C}} \text{hom}_{\mathcal{C}}(X, A \otimes Y) \times \text{hom}_{\mathcal{C}}(A \otimes R, S)$$

- Needed for probabilistic open games etc
- Universal property: “freely adding counits”
- Mitchell Riley, Categories of Optics, arXiv

The context functors

- $\mathbb{V} : \mathbf{PC} \rightarrow \mathbf{Set}, (X, S) \mapsto X, \ell \mapsto v_\ell$
 - It's the **view fibration** of a lens
 - $\mathbb{V} \cong \mathbf{hom}_{\mathbf{PC}}(I, -)$

The context functors

- $\mathbb{V} : \mathbf{PC} \rightarrow \mathbf{Set}, (X, S) \mapsto X, \ell \mapsto v_\ell$
 - It's the **view fibration** of a lens
 - $\mathbb{V} \cong \text{hom}_{\mathbf{PC}}(I, -)$
- $\mathbb{K} : \mathbf{PC}^{\text{op}} \rightarrow \mathbf{Set}, (X, S) \mapsto X \rightarrow S$
 - The **continuation functor**
 - $\mathbb{K} \cong \text{hom}_{\mathbf{PC}}(-, I)$

The context functors

- $\mathbb{V} : \mathbf{PC} \rightarrow \mathbf{Set}, (X, S) \mapsto X, \ell \mapsto v_\ell$
 - It's the **view fibration** of a lens
 - $\mathbb{V} \cong \text{hom}_{\mathbf{PC}}(I, -)$
- $\mathbb{K} : \mathbf{PC}^{\text{op}} \rightarrow \mathbf{Set}, (X, S) \mapsto X \rightarrow S$
 - The **continuation functor**
 - $\mathbb{K} \cong \text{hom}_{\mathbf{PC}}(-, I)$

Slogan: **points** are **states**, **continuations** are **effects**

Defining open games

An open game $\mathcal{G} : \binom{X}{S} \rightarrow \binom{Y}{R}$ consists of:

- A set $\Sigma_{\mathcal{G}}$ of **strategy profiles**

Defining open games

An open game $\mathcal{G} : \binom{X}{S} \rightarrow \binom{Y}{R}$ consists of:

- A set $\Sigma_{\mathcal{G}}$ of **strategy profiles**
- For every $\sigma : \Sigma_{\mathcal{G}}$, a lens $\mathcal{G}(\sigma) : \binom{X}{S} \rightarrow \binom{Y}{R}$

Defining open games

An open game $\mathcal{G} : \binom{X}{S} \rightarrow \binom{Y}{R}$ consists of:

- A set $\Sigma_{\mathcal{G}}$ of **strategy profiles**
- For every $\sigma : \Sigma_{\mathcal{G}}$, a lens $\mathcal{G}(\sigma) : \binom{X}{S} \rightarrow \binom{Y}{R}$
- For every **context** $(h, k) : \mathbb{V}(\binom{X}{S}) \times \mathbb{K}(\binom{Y}{R})$, a set $\mathbf{E}_{\mathcal{G}}(h, k) \subseteq \Sigma_{\mathcal{G}}$ of **Nash equilibria**

Defining open games

An open game $\mathcal{G} : \binom{X}{S} \rightarrow \binom{Y}{R}$ consists of:

- A set $\Sigma_{\mathcal{G}}$ of **strategy profiles**
- For every $\sigma : \Sigma_{\mathcal{G}}$, a lens $\mathcal{G}(\sigma) : \binom{X}{S} \rightarrow \binom{Y}{R}$
- For every **context** $(h, k) : \mathbb{V}(\binom{X}{S}) \times \mathbb{K}(\binom{Y}{R})$, a set $\mathbf{E}_{\mathcal{G}}(h, k) \subseteq \Sigma_{\mathcal{G}}$ of **Nash equilibria**

Things that have been abstracted away: players, moves, payoffs, maximisation

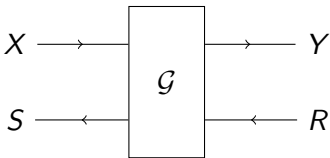
Defining open games

An open game $\mathcal{G} : (X_S) \rightarrow (Y_R)$ consists of:

- A set $\Sigma_{\mathcal{G}}$ of **strategy profiles**
- For every $\sigma : \Sigma_{\mathcal{G}}$, a lens $\mathcal{G}(\sigma) : (X_S) \rightarrow (Y_R)$
- For every **context** $(h, k) : \mathbb{V}(X_S) \times \mathbb{K}(Y_R)$, a set $\mathbf{E}_{\mathcal{G}}(h, k) \subseteq \Sigma_{\mathcal{G}}$ of **Nash equilibria**

Things that have been abstracted away: players, moves, payoffs, maximisation

We draw it like this:



Special open games

A **zero player** open game has $\Sigma_{\mathcal{G}} = 1$ and $\mathbf{E}_{\mathcal{G}}(h, k) = \{*\}$ for all (h, k)

- Zero-player open games $\binom{X}{S} \rightarrow \binom{Y}{R}$ are in bijection with lenses $\binom{X}{S} \rightarrow \binom{Y}{R}$

Special open games

A **zero player** open game has $\Sigma_{\mathcal{G}} = 1$ and $\mathbf{E}_{\mathcal{G}}(h, k) = \{*\}$ for all (h, k)

- Zero-player open games $\binom{X}{S} \rightarrow \binom{Y}{R}$ are in bijection with lenses $\binom{X}{S} \rightarrow \binom{Y}{R}$

A **scalar** open game is an open game $\binom{1}{1} \rightarrow \binom{1}{1}$

- They are determined by a set of strategy profiles, and a subset of Nash equilibria
- Every ordinary (eg. extensive form) game determines a scalar open game

Sequential play

Suppose we have open games

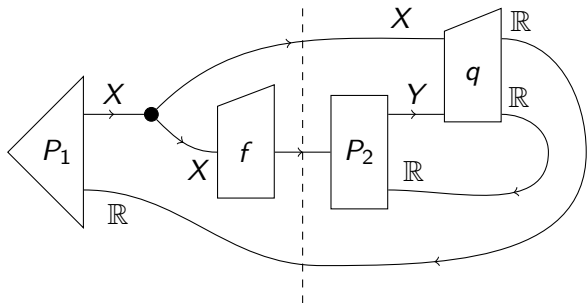
$$\begin{pmatrix} X \\ S \end{pmatrix} \xrightarrow{\mathcal{G}} \begin{pmatrix} Y \\ R \end{pmatrix} \xrightarrow{\mathcal{H}} \begin{pmatrix} Z \\ Q \end{pmatrix}$$

We define $\mathcal{H} \circ \mathcal{G} : \begin{pmatrix} X \\ S \end{pmatrix} \rightarrow \begin{pmatrix} Z \\ Q \end{pmatrix}$ like this:

- $\Sigma_{\mathcal{H} \circ \mathcal{G}} = \Sigma_{\mathcal{G}} \times \Sigma_{\mathcal{H}}$
- $(\mathcal{H} \circ \mathcal{G})(\sigma, \tau) = \mathcal{H}(\tau) \circ \mathcal{G}(\sigma)$
- The magic part:

$$\mathbf{E}_{\mathcal{H} \circ \mathcal{G}}(h, k) = \left\{ (\sigma, \tau) \mid \begin{array}{l} \sigma \in \mathbf{E}_{\mathcal{G}}(h, \mathbb{K}(\mathcal{H}(\tau))(k)) \\ \tau \in \mathbf{E}_{\mathcal{H}}(\mathbb{V}(\mathcal{G}(\sigma))(h), k) \end{array} \right\}$$

Example



$$\mathcal{G} : (1, 1) \rightarrow (X \times Z, \mathbb{R})$$

- $\Sigma_{\mathcal{G}} = X$
- $v_{\mathcal{G}(x)}(*) = (x, f(x))$
- $\mathbf{E}_{\mathcal{G}}(*, k) = \arg \max_x k(x, f(x))$

$$\mathcal{H} : (X \times Z, \mathbb{R}) \rightarrow (1, 1)$$

- $\Sigma_{\mathcal{H}} = Z \rightarrow Y$
- $u_{\mathcal{H}(\sigma)}((x, z), *) = q_1(x, \sigma(z))$
- $\mathbf{E}_{\mathcal{H}}((x, z), *) = \{\sigma \mid \sigma(z) \in \arg \max_y q_2(x, y)\}$

Simultaneous play

... is more complicated, cut for time

Finitely generated games

Define an open game $\mathcal{A}_{X,Y} : \binom{X}{1} \rightarrow \binom{Y}{\mathbb{R}}$ by

- $\Sigma_{\mathcal{A}_{X,Y}} = X \rightarrow Y$
- $v_{\mathcal{A}_{X,Y}}(\sigma) = \sigma$
- $\mathbf{E}_{\mathcal{A}_{X,Y}}(h, k) = \{\sigma \mid \sigma(h) \in \arg \max(k)\}$

It's (a single decision by) an **agent**

N.B. This is the only place we mention \mathbb{R} or $\arg \max$!

Finitely generated games

Define an open game $\mathcal{A}_{X,Y} : \left(\begin{smallmatrix} X \\ 1 \end{smallmatrix}\right) \rightarrow \left(\begin{smallmatrix} Y \\ \mathbb{R} \end{smallmatrix}\right)$ by

- $\Sigma_{\mathcal{A}_{X,Y}} = X \rightarrow Y$
- $v_{\mathcal{A}_{X,Y}}(\sigma) = \sigma$
- $\mathbf{E}_{\mathcal{A}_{X,Y}}(h, k) = \{\sigma \mid \sigma(h) \in \arg \max(k)\}$

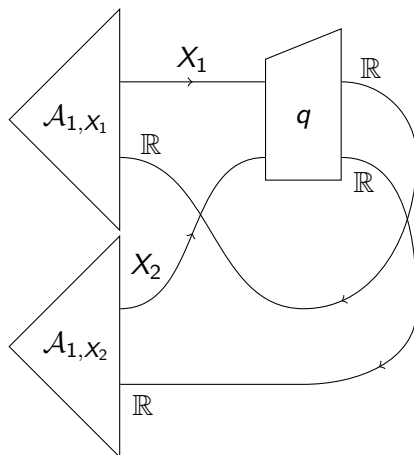
It's (a single decision by) an **agent**

N.B. This is the only place we mention \mathbb{R} or $\arg \max$!

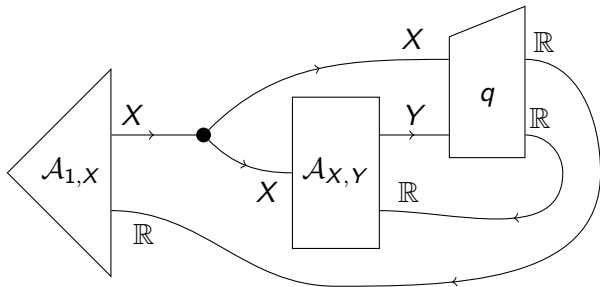
Fundamental theorem of compositional game theory: The following are in (sensible) bijective correspondence:

- 1 Scalar open games finitely generated by zero-player open games, $\mathcal{A}_{X,Y}$, \circ and \otimes
- 2 Strategy profiles & pure Nash equilibria of finite-depth extensive form games of imperfect information

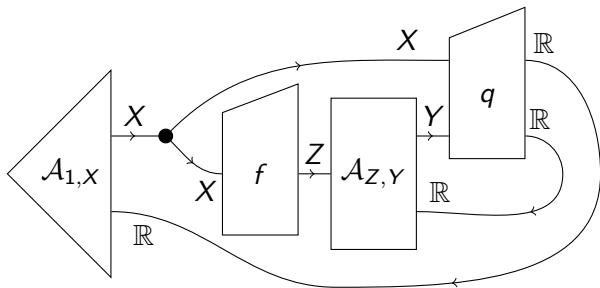
Bimatrix game



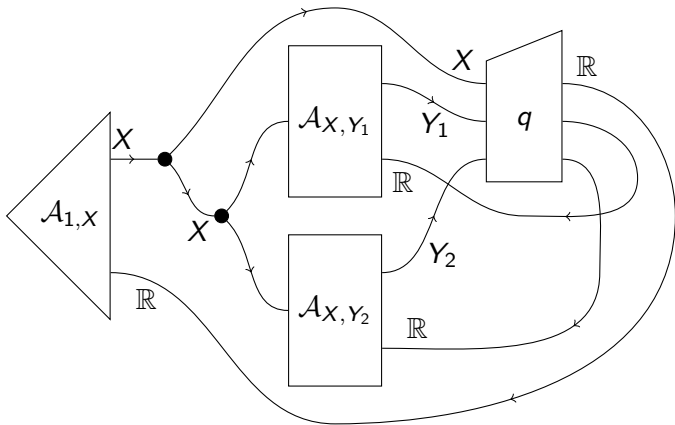
Sequential game of perfect information



Sequential game of imperfect information



Hybrid sequential-simultaneous game



Cool stuff in the past

- Morphisms of open games, version 1:
 - infinitely repeated games are final coalgebras

Cool stuff in the past

- Morphisms of open games, version 1:
 - infinitely repeated games are final coalgebras
- Morphisms between open games, version 2:
 - Nash equilibria are states
 - Subgame perfect equilibria are \otimes -separable states
 - Products are external choice

Cool stuff in the past

- Morphisms of open games, version 1:
 - infinitely repeated games are final coalgebras
- Morphisms between open games, version 2:
 - Nash equilibria are states
 - Subgame perfect equilibria are \otimes -separable states
 - Products are external choice
- Bayesian open games
 - (not released yet)
 - Unexpectedly hard

Cool stuff in the future

- Compositional economic modelling

Cool stuff in the future

- Compositional economic modelling
- Composing numerical solution methods

Cool stuff in the future

- Compositional economic modelling
- Composing numerical solution methods
- Connections with learning
 - Using deep learning to cheat complexity theory

Cool stuff in the future

- Compositional economic modelling
- Composing numerical solution methods
- Connections with learning
 - Using deep learning to cheat complexity theory
- Open graphical games

Cool stuff in the future

- Compositional economic modelling
- Composing numerical solution methods
- Connections with learning
 - Using deep learning to cheat complexity theory
- Open graphical games
- Getting a compact closed category
 - Version 1: **PC** \leftrightarrow **Int**
 - Version 2: **PC** \leftrightarrow **Span(PC)**