

# Change Actions

## Models of Generalised Differentiation

Mario Alvarez-Picallo  
C.-H. L. Ong

Department of Computer Science, University of Oxford



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# Incremental computation with derivatives

- Objective: compute the value of an (expensive) function  $f$
- Input  $x$  changes over time:  $x_1, x_2, \dots$
- *How to update the value of  $f(x)$  as  $x_i$  changes?*

# Incremental computation with derivatives

- Interpret the  $x_i$  as applying successive “updates”  $\delta x_i$  to an initial value  $x_1$ :

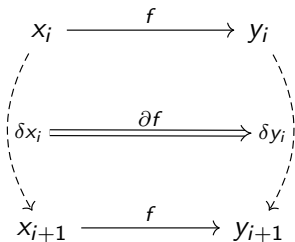
$$x_2 = x_1 \oplus \delta x_1$$

$$x_3 = x_2 \oplus \delta x_2 \dots$$

- Find  $\delta y_i$  such that:

$$f(x_2) = f(x_1 \oplus \delta x_1) = f(x_1) \oplus \delta y_1$$

$$f(x_3) = f(x_2 \oplus \delta x_2) = f(x_2) \oplus \delta y_2 \dots$$



## Change action

A **change action**  $\bar{A}$  (in a Cartesian category  $\mathbf{C}$ ) is a tuple  $(A, \Delta A, \oplus, +, 0)$  such that:

- $(\Delta A, +, 0)$  is a monoid
- $\oplus : A \times \Delta A \rightarrow A$  is an action of  $\Delta A$  on  $A$ , i.e.:
  - 1  $a \oplus 0 = a$
  - 2  $a \oplus (\delta a + \delta b) = (a \oplus \delta a) \oplus \delta b$

## Change actions

Given change actions  $\overline{A}, \overline{B}$  and a map  $f : A \rightarrow B$ , a **derivative** for  $f$  is a function  $\partial f : A \times \Delta A \rightarrow \Delta B$  such that:

- $f(a \oplus \delta a) = f(a) \oplus \partial f(a, \delta a)$
- $\partial f(a, 0_A) = 0_B$
- $\partial f(a, \delta a + \delta b) = \partial f(a, \delta a) + \partial f(a \oplus \delta a, \delta b)$

What we *don't* require:

- Linearity
- Uniqueness!

Diagrammatically:

$$\begin{array}{ccc} A \times \Delta A & \xrightarrow{\langle f \circ \pi_1, \partial f \rangle} & B \times \Delta B \\ \downarrow \oplus_A & & \downarrow \oplus_B \\ A & \xrightarrow{f} & B \end{array}$$

Condition 1 essentially says:  $\oplus$  is a natural transformation!

# The chain rule

## Theorem

Given  $f : A \rightarrow B, g : B \rightarrow C$  differentiable maps with derivatives  $\partial f, \partial g$ , then  $\partial g(f(a), \partial f(a, \delta a))$  is a derivative for  $g \circ f$

$$\begin{array}{ccccc} & & \langle (g \circ f) \circ \pi_1, \partial g \circ \langle f \circ \pi_1, \partial f \rangle \rangle & & \\ & \swarrow & & \searrow & \\ A \times \Delta A & \xrightarrow{\langle f \circ \pi_1, \partial f \rangle} & B \times \Delta B & \xrightarrow{\langle g \circ \pi_1, \partial g \rangle} & C \times \Delta C \\ \oplus_A \downarrow & & \downarrow \oplus_B & & \downarrow \oplus_C \\ A & \xrightarrow{f} & B & \xrightarrow{g} & C \\ & \searrow & & \swarrow & \\ & & g \circ f & & \end{array}$$

# A category of change actions

## The category $\mathbf{CAct}(\mathbf{C})$

Given a Cartesian category  $\mathbf{C}$ , we define the category  $\mathbf{CAct}(\mathbf{C})$  as follows:

- Objects of  $\mathbf{CAct}(\mathbf{C})$ : all  $\mathbf{C}$ -change actions  
 $\bar{A} = (A, \Delta A, \oplus, +, 0)$
- Morphisms  $\bar{f} : \bar{A} \rightarrow \bar{B}$ : pairs  $(f, \partial f)$  of  $\mathbf{C}$ -map  $f$  and derivative for  $f$ .
- Identities:  $\bar{\text{Id}} = (\text{Id}, \pi_2)$
- Composition: chain rule!

## Lemma

The above induces an endofunctor  $\mathbf{CAct} : \mathbf{Cat}_x \rightarrow \mathbf{Cat}_x$



## Product of change actions

Given change actions  $\bar{A}, \bar{B}$ , their product  $\bar{A} \times \bar{B}$  is given by:

$$\bar{A} \times \bar{B} = (A \times B, \Delta A \times \Delta B, \oplus_{\times}, +_{\times}, 0_{\times})$$

$$(a, b) \oplus_{\times} (\delta a, \delta b) = (a \oplus_A \delta a, b \oplus_B \delta b)$$

$$(\delta a_1, \delta b_1) +_{\times} (\delta a_2, \delta b_2) = (\delta a_1 +_A \delta a_2, \delta b_1 +_B \delta b_2)$$

$$0_{\times} = (0_A, 0_B)$$

Terminal object:  $\bar{T} = (T, T, \dots)$

# Coproducts in $\mathbf{CAct}(\mathbf{C})$

Whenever  $\mathbf{C}$  has (distributive) coproducts, so does  $\mathbf{CAct}(\mathbf{C})$ !

## Coproduct of change actions

Given difference algebras  $\bar{A}, \bar{B}$ , their coproduct difference algebra  $\bar{A} + \bar{B}$  is given by:

$$\bar{A} + \bar{B} = (A + B, \Delta A \times \Delta B, \oplus_+, ++, 0_+)$$

$$a \oplus_+ (\delta a, \delta b) = a \oplus_A \delta a$$

$$b \oplus_+ (\delta a, \delta b) = b \oplus_B \delta b$$

$$(\delta a_1, \delta b_1) ++ (\delta a_2, \delta b_2) = (da_1 +_A \delta a_2, \delta b_1 +_B \delta b_2)$$

$$0_+ = (0_A, 0_B)$$

Initial object:  $\bar{\perp} = (\perp, \top, \dots)$

(Corollary: the derivative of a constant map is 0!)

# Higher-order derivatives

- All derivatives so far: first-order!
  - No  $\partial\partial f$
- How to get higher order derivatives?
  - Idea: make  $\Delta A$  a change action

## Change action models

A change action model on a Cartesian category  $\mathbf{C}$  is a section  $\alpha : \mathbf{C} \rightarrow \mathbf{CAct}(\mathbf{C})$  of the obvious forgetful functor  $\epsilon$ , that is,  $\alpha$  is a product-preserving functor from  $\mathbf{C}$  into  $\mathbf{CAct}(\mathbf{C})$  such that  $\epsilon \circ \alpha = \text{Id}$

Notation: when  $A$  is a  $\mathbf{C}$ -object, we use  $\Delta A, \oplus, +, 0$  for those in  $\alpha(A)$  - same for  $f$ .

# Higher-order derivatives

Some consequences of the previous definition:

- Higher-order derivatives

$$f : A \rightarrow B \Rightarrow \alpha(f) = (f, \partial f) : \alpha(A) \rightarrow \alpha(B)$$

$$\partial f : A \times \Delta A \rightarrow \Delta B \Rightarrow \alpha(\partial f) = (\partial f, \partial^2 f) : \alpha(A \times \Delta A) \rightarrow \alpha(\Delta B)$$

$$\partial^2 f : (A \times \Delta A) \times (\Delta A \times \Delta^2 A) \rightarrow \Delta^2 B \Rightarrow \dots$$

- “Structure” maps are all differentiable
  - $\partial \oplus, \partial +, \dots$
- “Tangent bundle” functor  $\mathbf{T}$  (in fact a monad)

$$\mathbf{T}A = A \times \Delta A$$

$$\mathbf{T}f = \langle f \circ \pi_1, \partial f \rangle$$

## Internalization

Whenever  $\mathbf{C}$  is a CCC, there is a morphism

$\mathbf{d} : (A \Rightarrow B) \rightarrow (A \times \Delta A) \Rightarrow \Delta B$  such that, for every map  $f : A \rightarrow B$ , we have

$$\mathbf{d} \circ \Lambda f = \Lambda(\partial f)$$

Essentially: *the derivative operator is itself a  $\mathbf{C}$ -map*

## Lemma

When  $\mathbf{T}$  is representable, the tangent bundle  $\mathbf{T}(A \Rightarrow B)$  is naturally isomorphic to  $A \Rightarrow \mathbf{T}B$ . Furthermore, the following diagram commutes:

$$\begin{array}{ccc} \mathbf{T}(A \Rightarrow B) & \xrightarrow{\cong} & A \Rightarrow \mathbf{T}B \\ \oplus_{A \Rightarrow B} \downarrow & \swarrow \text{Id}_{A \Rightarrow \oplus B} & \\ A \Rightarrow B & & \end{array}$$

# Examples of change action models

Are there actually any such objects? Yes!

- “Free” models
- Cartesian differential categories (somewhat)
- Calculus on groups
- Commutative Kleene algebras

# “Free” models

- Problem:  $\mathbf{CAct}(\mathbf{C})$  doesn't have enough “higher” structure
- Solution: just add it!

## $\omega$ -change actions

The category of  $\omega$ -change actions on  $\mathbf{C}$   $\mathbf{CAct}_\omega(\mathbf{C})$  is defined as the limit in  $\mathbf{Cat}_\times$  of the following diagram:

$$\begin{array}{c} \mathbf{CAct}_\omega(\mathbf{C}) \\ \downarrow \quad \searrow \quad \swarrow \\ \mathbf{CAct}(\mathbf{C}) \quad \mathbf{CAct}^2(\mathbf{C}) \quad \mathbf{CAct}^3(\mathbf{C}) \quad \dots \\ \leftarrow \begin{array}{c} \varepsilon \\ \hline \xi \end{array} \leftarrow \begin{array}{c} \varepsilon \\ \hline \xi \end{array} \leftarrow \begin{array}{c} \varepsilon \\ \hline \xi \end{array} \leftarrow \dots \end{array}$$

When you unpack it - very similar to Fáa di Bruno (Cockett, Seely 2011)

# “Free” models

## Two “forgetful” functors

$$\varepsilon : \mathbf{CAct}(\mathbf{C}) \rightarrow \mathbf{C}$$

$$\varepsilon(A, \Delta A, \oplus, +, 0) = A$$

$$\xi : \mathbf{CAct}^2(\mathbf{C}) \rightarrow \mathbf{CAct}(\mathbf{C})$$

$$\xi((A, \dots), (\Delta A, \dots), \oplus, +, 0) = (A, \Delta A, \oplus, +, 0)$$

Intuitively:  $\varepsilon$  forgets the higher structure,  $\xi$  prefers it

## The canonical model

There is a “canonical” change action model

$\gamma : \mathbf{CAct}_\omega(\mathbf{C}) \rightarrow \mathbf{CAct}(\mathbf{CAct}_\omega(\mathbf{C}))$ . Furthermore, whenever  $\mathbf{C}$  is a CCC then so is  $\mathbf{CAct}_\omega$ , and the tangent bundle functor  $\mathbf{T}$  is representable.



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or all change action models on  $\mathbf{C}$ ,  $\alpha : \mathbf{C} \rightarrow \mathbf{CAct}(\mathbf{C})$ , there is a unique functor  $\alpha_\omega : \mathbf{C} \rightarrow \mathbf{CAct}_\omega(\mathbf{C})$  making the following diagram commute

$$\begin{array}{ccc}
 \mathbf{C} & \xrightarrow{\alpha} & \mathbf{CAct}(\mathbf{C}) \\
 \exists! \alpha_\omega \downarrow & & \downarrow \mathbf{CAct}(\alpha_\omega) \\
 \mathbf{CAct}_\omega(\mathbf{C}) & \xrightarrow{\gamma} & \mathbf{CAct}(\mathbf{CAct}_\omega(\mathbf{C}))
 \end{array}$$

Intuitively: every change action model on  $\mathbf{C}$  can be understood entirely through its embedding into  $\mathbf{CAct}_\omega(\mathbf{C})$

# Models from Cartesian differential categories

Cartesian differential categories (Blute, Cockett, Seely 2009)

- Axiomatise abstract derivatives
- Examples: smooth maps between vector spaces
- Recent generalisation (Cruttwell 2017)

## Generalised Cartesian differential category (Cruttwell 2017)

A generalised Cartesian differential category is a Cartesian category  $\mathbf{C}$  and:

- For every object  $A$ , a commutative monoid  $(L(A), +, 0)$
- For every map  $f : A \rightarrow B$ , a map  $Df : A \times L(A) \rightarrow L(B)$
- Some equations...

## Lemma

In a GCDC, define the tangent bundle functor  $\mathbf{T}$  by:

$$\mathbf{T}A = A \times L(A)$$

$$\mathbf{T}f = \langle f \circ \pi_1, Df \rangle$$

$\mathbf{T}$  is a monad in  $\mathbf{C}$

Kleisli category of  $\mathbf{T}$ : “generalised vector fields”

## Theorem

Given a GCDC  $\mathbf{C}$ , the Kleisli category  $\mathbf{C}_{\mathbf{T}A}$  can be extended to a change action model

## The category **CGrp**

The category **CGrp** is defined by:

- The objects of **CGrp** are groups (in **Set**)
- A morphism  $f : (A, +_A, 0_A) \rightarrow (B, +_B, 0_B)$  is a (set-theoretic) function  $f : A \rightarrow B$

## Theorem

The category **CGrp** can be extended to a change action model by defining  $\alpha : \mathbf{CGrp} \rightarrow \mathbf{CAct}(\mathbf{CGrp})$  as follows:

- $\alpha(A, +_A, 0_A) = (A, A, +_A, +_A, 0_A)$
- $\alpha(f)(a, \delta a) = -f(a) + f(a + \delta a)$

# Calculus on groups

Seemingly trivial, but already studied...under two different names!

Boolean differential calculus (Steinbach 2017)

- Calculus on Boolean algebras
- Treat Boolean algebra like a group with **XOR**
- Differential of  $f$ :  $f(x)$  **XOR**  $f(x \text{ XOR } dx)$
- Precisely derivatives in  $(\mathbb{B}, \mathbb{B}, \text{XOR}, \text{XOR}, 0)$

Calculus of finite differences (Jordan 1965)

- Calculus techniques on integers
- Finite difference operator  $\Delta f(x) = f(x + 1) - f(x)$
- Precisely derivatives in  $(\mathbb{Z}, \mathbb{Z}, +, +, 0)$  evaluated “along” 1
- We recover the chain rule!

# Commutative Kleene algebras

## Derivatives of polynomials on CKAs

Let  $\mathbb{K}$  be a commutative Kleene algebra. Given a polynomial  $p = p(\bar{x})$  on  $\mathbb{K}$ , we define its  $i$ -th derivative  $\frac{\partial p}{\partial x_i}(\bar{x}) \in \mathbb{K}[\bar{x}]$ :

$$\frac{\partial p^*}{\partial x_i}(\bar{x}) = p^*(\bar{x}) \frac{\partial p}{\partial x_i}(\bar{x})$$

$$\frac{\partial (p + q)}{\partial x_i}(\bar{x}) = \frac{\partial p}{\partial x_i}(\bar{x}) + \frac{\partial q}{\partial x_i}(\bar{x})$$

$$\frac{\partial (p q)}{\partial x_i}(\bar{x}) = p(\bar{x}) \frac{\partial q}{\partial x_i}(\bar{x}) + q(\bar{x}) \frac{\partial p}{\partial x_i}(\bar{x})$$

## Taylor's formula (Hopkins, Kozen 1999)

Whenever  $p(x) \in \mathbb{K}[x]$ , we have  $p(a + b) = p(a) + b \frac{\partial p}{\partial x}(a + b)$

## Finite powers of Kleene algebras

Let  $\mathbb{K}$  be a commutative Kleene algebra. We define the category  $\mathbb{K}_\times$  as the Cartesian category whose objects are all finite powers of  $\mathbb{K}$  and whose arrows are polynomials on  $\mathbb{K}$ .

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The category  $\mathbb{K}_\times$  can be endowed with a change action model  $\alpha : \mathbb{K}_\times \rightarrow \text{CAct}(\mathbb{K}_\times)$  given by:

- $\alpha(\mathbb{K}) = (\mathbb{K}, \mathbb{K}, +, +, 0)$
- $\alpha(p(x_1, \dots, x_n)) = \sum_{i=1}^n y_i \frac{\partial p}{\partial x_i}(x_1 + y_1, \dots, x_n + y_n)$

So far:

- Change actions as models for H-O differentiation
- Well-behaved, pop up everywhere
- Related to GCDC, but different

In the future:

- Interesting 2-categorical story!
- Calculus - incremental System T?
- Do more geometry with this!
- Gradients
  - $f(a) \oplus \delta b = f(a \oplus \nabla(a, \delta b))$
  - Composes, gives rise to category
  - Related to (Van Laarhoven) lenses